## **SIEMENS**

## Data sheet

## 6ES7515-2UM01-0AB0

SIMATIC S7-1500T, CPU 1515TF-2 PN, Central processing unit with work memory 750 KB for program and 3 MB for data, 1st interface: PROFINET IRT with 2-port switch, 2nd interface, Ethernet, 30 ns bit performance, SIMATIC Memory Card required



Product type designation	CPU 1515TF-2 PN
HW functional status	FS03
Firmware version	V2.8
Product function	
● I&M data	Yes; I&M0 to I&M3
<ul> <li>Isochronous mode</li> </ul>	Yes; Distributed and central; with minimum OB 6x cycle of 500 $\mu s$ (distributed) and 1 ms (central)
Engineering with	
<ul> <li>STEP 7 TIA Portal configurable/integrated from version</li> </ul>	V16 (FW V2.8) / as of V14 (FW V2.1)
Configuration control	
via dataset	Yes
Display	
Screen diagonal [cm]	6.1 cm
Control elements	
Number of keys	6
Mode selector switch	1

General information

Supply voltage	
Type of supply voltage	24 V DC
permissible range, lower limit (DC)	19.2 V
permissible range, upper limit (DC)	28.8 V
Reverse polarity protection	Yes
Mains buffering	
<ul> <li>Mains/voltage failure stored energy time</li> </ul>	5 ms
• Repeat rate, min.	1/s
Input current	0.8 A
Current consumption (rated value)	
Inrush current, max.	2.4 A; Rated value 0.02 A <sup>2</sup> ·s
IT.	0.02 A-·S
Power	
Infeed power to the backplane bus	12 W
Power consumption from the backplane bus	6.2 W
(balanced)	
Power loss	
Power loss, typ.	6.3 W
Number of slots for SIMATIC memory card	1
SIMATIC memory card required	Yes
Work memory	750 l/b.4.
• integrated (for program)	750 kbyte
• integrated (for data)	3 Mbyte
Load memory	
Plug-in (SIMATIC Memory Card), max.	32 Gbyte
Backup	
maintenance-free	Yes
CPU processing times	
for bit operations, typ.	30 ns
for word operations, typ.	36 ns
for fixed point arithmetic, typ.	48 ns
for floating point arithmetic, typ.	192 ns
CPU-blocks Number of elements (total)	6 000; Blocks (OB, FB, FC, DB) and UDTs
DB	
Number range	1 60 999; subdivided into: number range that can be used by
• Number range	the user: 1 59 999, and number range of DBs created via SFC 86: 60 000 60 999
• Size, max.	3 Mbyte; For DBs with absolute addressing, the max. size is 64 KB

FB	
Number range	0 65 535
• Size, max.	500 kbyte
FC	
Number range	0 65 535
• Size, max.	500 kbyte
OB	
• Size, max.	500 kbyte
<ul> <li>Number of free cycle OBs</li> </ul>	100
<ul> <li>Number of time alarm OBs</li> </ul>	20
<ul> <li>Number of delay alarm OBs</li> </ul>	20
<ul> <li>Number of cyclic interrupt OBs</li> </ul>	20; With minimum OB 3x cycle of 500 µs
<ul> <li>Number of process alarm OBs</li> </ul>	50
<ul> <li>Number of DPV1 alarm OBs</li> </ul>	3
<ul> <li>Number of isochronous mode OBs</li> </ul>	2
<ul> <li>Number of technology synchronous alarm OBs</li> </ul>	2
<ul> <li>Number of startup OBs</li> </ul>	100
<ul> <li>Number of asynchronous error OBs</li> </ul>	4
<ul> <li>Number of synchronous error OBs</li> </ul>	2
<ul> <li>Number of diagnostic alarm OBs</li> </ul>	1
Nesting depth	
• per priority class	24; Up to 8 possible for F-blocks
Counters, timers and their retentivity	
S7 counter	
• Number	2 048
Retentivity	
— adjustable	Yes
IEC counter	
• Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
S7 times	
• Number	2 048
Retentivity	
— adjustable	Yes
IEC timer	
• Number	Any (only limited by the main memory)
Retentivity	
— adjustable	Yes
Data areas and their retentivity	

Retentive data area (incl. timers, counters, flags),	512 kbyte; In total; available retentive memory for bit memories,
max.	timers, counters, DBs, and technology data (axes): 472 KB
Extended retentive data area (incl. timers, counters,	3 Mbyte; When using PS 6 0W 24/48/60 V DC HF
flags), max.	
Flag	
<ul> <li>Number, max.</li> </ul>	16 kbyte
<ul> <li>Number of clock memories</li> </ul>	8; 8 clock memory bit, grouped into one clock memory byte
Data blocks	
<ul> <li>Retentivity adjustable</li> </ul>	Yes
<ul> <li>Retentivity preset</li> </ul>	No
Local data	
<ul> <li>per priority class, max.</li> </ul>	64 kbyte; max. 16 KB per block
Address area	
Number of IO modules	8 192; max. number of modules / submodules
I/O address area	
Inputs	32 kbyte; All inputs are in the process image
Outputs	32 kbyte; All outputs are in the process image
per integrated IO subsystem	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
per CM/CP	
— Inputs (volume)	8 kbyte
— Outputs (volume)	8 kbyte
Subprocess images	
<ul> <li>Number of subprocess images, max.</li> </ul>	32
Hardware configuration	
Number of distributed IO systems	64; A distributed I/O system is characterized not only by the integration of distributed I/O via PROFINET or PROFIBUS communication modules, but also by the connection of I/O via AS-i master modules or links (e.g. IE/PB-Link)
Number of DP masters	
● Via CM	8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Number of IO Controllers	
• integrated	2
• Via CM	8; A maximum of 8 CMs/CPs (PROFIBUS, PROFINET, Ethernet) can be inserted in total
Rack	
<ul> <li>Modules per rack, max.</li> </ul>	32; CPU + 31 modules
• Number of lines, max.	1
PtP CM	
Number of PtP CMs	the number of connectable PtP CMs is only limited by the number of available slots

Time of day	
Clock	
• Туре	Hardware clock
Backup time	6 wk; At 40 °C ambient temperature, typically
<ul> <li>Deviation per day, max.</li> </ul>	10 s; Typ.: 2 s
Operating hours counter	
• Number	16
Clock synchronization	
• supported	Yes
• in AS, master	Yes
• in AS, slave	Yes
<ul> <li>on Ethernet via NTP</li> </ul>	Yes
nterfaces	
Number of PROFINET interfaces	2
I. Interface	
Interface types	
Number of ports	2
<ul> <li>integrated switch</li> </ul>	Yes
• RJ 45 (Ethernet)	Yes; X1
Protocols	
IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
<ul> <li>SIMATIC communication</li> </ul>	Yes
<ul> <li>Open IE communication</li> </ul>	Yes; Optionally also encrypted
Web server	Yes
<ul> <li>Media redundancy</li> </ul>	Yes
PROFINET IO Controller	
Services	
— PG/OP communication	Yes
— S7 routing	Yes
— Isochronous mode	Yes
— Direct data exchange	Yes; Requirement: IRT and isochronous mode (MRPD optional)
— IRT	Yes
— MRP	Yes; MRP Automanager acc. to IEC 62439-2 Edition 2.0; MRP Manager; MRP Client; max. number of devices in the ring: 50
— MRPD	Yes; Requirement: IRT
— PROFlenergy	Yes; per user program
— Prioritized startup	Yes; Max. 32 PROFINET devices
— Number of connectable IO Devices, max.	256; In total, up to 1 000 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET

— Of which IO devices with IRT, max.	64
— Number of connectable IO Devices for RT,	256
max.	
— of which in line, max.	256
— Number of IO Devices that can be	8; in total across all interfaces
simultaneously activated/deactivated, max.	
— Number of IO Devices per tool, max.	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Update time for IRT	
— for send cycle of 250 μs	250 $\mu s$ to 4 ms; Note: In the case of IRT with isochronous mode, the minimum update time of 500 $\mu s$ of the isochronous OB is decisive
— for send cycle of 500 µs	500 µs to 8 ms
— for send cycle of 1 ms	1 ms to 16 ms
— for send cycle of 2 ms	2 ms to 32 ms
— for send cycle of 4 ms	4 ms to 64 ms
<ul> <li>— With IRT and parameterization of "odd" send cycles</li> </ul>	Update time = set "odd" send clock (any multiple of 125 $\mu s$ : 375 $\mu s$ , 625 $\mu s$ 3 875 $\mu s$ )
Update time for RT	
— for send cycle of 250 μs	250 μs to 128 ms
— for send cycle of 500 μs	500 µs to 256 ms
— for send cycle of 1 ms	1 ms to 512 ms
— for send cycle of 2 ms	2 ms to 512 ms
— for send cycle of 4 ms	4 ms to 512 ms
PROFINET IO Device	
Services	
— PG/OP communication	Yes
— S7 routing	Yes
— Isochronous mode	No
— IRT	Yes
— MRP	Yes; MRP Automanager acc. to IEC 62439-2 Edition 2.0; MRP Manager; MRP Client; max. number of devices in the ring: 50
— MRPD	Yes; Requirement: IRT
— PROFlenergy	Yes; per user program
— Shared device	Yes
<ul> <li>— Number of IO Controllers with shared device, max.</li> </ul>	4
— Asset management record	Yes; per user program
2. Interface	
Interface types	
Number of ports	1

<ul> <li>integrated switch</li> </ul>	No
• RJ 45 (Ethernet)	Yes; X2
Protocols	
IP protocol	Yes; IPv4
PROFINET IO Controller	Yes
PROFINET IO Device	Yes
SIMATIC communication	Yes
Open IE communication	Yes; Optionally also encrypted
Web server	Yes
Media redundancy	No
PROFINET IO Controller	
Services	
— PG/OP communication	Yes
— S7 routing	Yes
— Isochronous mode	No
— Direct data exchange	Yes
— IRT	No
— MRP	No
— MRPD	No
— PROFlenergy	Yes; per user program
— Prioritized startup	No
— Number of connectable IO Devices, max.	32; In total, up to 1 000 distributed I/O devices can be connected via AS-i, PROFIBUS or PROFINET
<ul> <li>— Number of connectable IO Devices for RT, max.</li> </ul>	32
— of which in line, max.	32
<ul> <li>— Number of IO Devices that can be simultaneously activated/deactivated, max.</li> </ul>	8; in total across all interfaces
- Number of IO Devices per tool, max.	8
— Updating times	The minimum value of the update time also depends on communication share set for PROFINET IO, on the number of IO devices, and on the quantity of configured user data
Update time for RT	
— for send cycle of 1 ms	1 ms to 512 ms
PROFINET IO Device	
Services	
— PG/OP communication	Yes
— S7 routing	Yes
— Isochronous mode	No
— IRT	No
— MRP	No
— MRPD	No

- PROFlenergy	Yes; per user program
— Prioritized startup	No
— Shared device	Yes
— Number of IO Controllers with shared	4
device, max.	
— Asset management record	Yes; per user program

Interface types	
RJ 45 (Ethernet)	
• 100 Mbps	Yes
<ul> <li>Autonegotiation</li> </ul>	Yes
Autocrossing	Yes
<ul> <li>Industrial Ethernet status LED</li> </ul>	Yes

Protocols	
Number of connections	
<ul> <li>Number of connections, max.</li> </ul>	192; via integrated interfaces of the CPU and connected CPs / CMs
<ul> <li>Number of connections reserved for ES/HMI/web</li> </ul>	10
<ul> <li>Number of connections via integrated interfaces</li> </ul>	108
<ul> <li>Number of S7 routing paths</li> </ul>	16
Redundancy mode	
<ul> <li>H-Sync forwarding</li> </ul>	Yes
Media redundancy	
— Switchover time on line break, typ.	200 ms; For MRP, bumpless for MRPD
— Number of stations in the ring, max.	50
SIMATIC communication	
<ul> <li>S7 communication, as server</li> </ul>	Yes
<ul> <li>S7 communication, as client</li> </ul>	Yes
<ul> <li>User data per job, max.</li> </ul>	See online help (S7 communication, user data size)
Open IE communication	
• TCP/IP	Yes
— Data length, max.	64 kbyte
<ul> <li>several passive connections per port, supported</li> </ul>	Yes
• ISO-on-TCP (RFC1006)	Yes
— Data length, max.	64 kbyte
• UDP	Yes
— Data length, max.	2 kbyte; 1 472 bytes for UDP broadcast
— UDP multicast	Yes; Max. 5 multicast circuits
• DHCP	No
• SNMP	Yes

Destaut

• DCP	Yes
• LLDP	Yes
Web server	
• HTTP	Yes; Standard and user pages
• HTTPS	Yes; Standard and user pages
OPC UA	
Runtime license required	Yes
OPC UA Client	Yes
— Application authentication	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— User authentication	"anonymous" or by user name & password
— Number of connections, max.	10
<ul> <li>Number of nodes of the client interfaces, max.</li> </ul>	2 000
<ul> <li>— Number of elements for one call of OPC_UA_NodeGetHandleList/OPC_UA_Rea dList/OPC_UA_WriteList, max.</li> </ul>	300
<ul> <li>— Number of elements for one call of OPC_UA_NameSpaceGetIndexList, max.</li> </ul>	20
<ul> <li>— Number of elements for one call of OPC_UA_MethodGetHandleList, max.</li> </ul>	100
<ul> <li>— Number of simultaneous calls of the client instructions per connection (except OPC_UA_ReadList,OPC_UA_WriteList,OPC_ UA_MethodCall), max.</li> </ul>	1
<ul> <li>Number of simultaneous calls of the client instructions</li> <li>OPC_UA_ReadList,OPC_UA_WriteList and OPC_UA_MethodCall, max.</li> </ul>	5
<ul> <li>— Number of registerable nodes, max.</li> </ul>	5 000
<ul> <li>Number of registerable method calls of OPC_UA_MethodCall, max.</li> </ul>	100
<ul> <li>— Number of inputs/outputs when calling OPC_UA_MethodCall, max.</li> </ul>	20
OPC UA Server	Yes; Data access (read, write, subscribe), method call, custom address space
— Application authentication	Yes
— Security policies	Available security policies: None, Basic128Rsa15, Basic256Rsa15, Basic256Sha256
— User authentication	"anonymous" or by user name & password
— Number of sessions, max.	48
— Number of accessible variables, max.	100 000
<ul> <li>Number of registerable nodes, max.</li> </ul>	20 000

<ul> <li>Number of subscriptions per session, max.</li> </ul>	20
— Sampling interval, min.	100 ms
— Publishing interval, min.	200 ms
- Number of server methods, max.	50
— Number of inputs/outputs per server	20
method, max.	
- Number of monitored items, max.	2 000; for 1 s sampling interval and 1 s send interval
- Number of server interfaces, max.	10; or 20, depending on type of server interface
<ul> <li>— Number of nodes for user-defined server</li> </ul>	5 000
interfaces, max.	
Further protocols	
• MODBUS	Yes; MODBUS TCP
Isochronous mode	
Equidistance	Yes
S7 message functions	
Number of login stations for message functions, max.	64
Program alarms	Yes
Number of configurable program messages, max.	10 000; Program messages are generated by the
	"Program_Alarm" block, ProDiag or GRAPH
Number of loadable program messages in RUN,	5 000
max.	
Number of simultaneously active program alarms	
<ul> <li>Number of program alarms</li> </ul>	800
<ul> <li>Number of alarms for system diagnostics</li> </ul>	200
Number of alarms for motion technology	160
objects	
Test commissioning functions	
Joint commission (Team Engineering)	Yes; Parallel online access possible for up to 8 engineering systems
Status block	Yes; Up to 8 simultaneously (in total across all ES clients)
Single step	No
Number of breakpoints	8
Status/control	
Status/control variable	Yes
• Variables	Inputs/outputs, memory bits, DBs, distributed I/Os, timers, counters
<ul> <li>Number of variables, max.</li> </ul>	
— of which status variables, max.	200; per job
— of which control variables, max.	200; per job
Forcing	
Forcing, variables	Peripheral inputs/outputs
<ul> <li>Number of variables, max.</li> </ul>	200

Present Yes     Number of entries, max. 3200     - of which powerfal-proof 500 Traces     Number of configurable Traces 4: Up to 512 KB of data per trace are possible Interrupts/diagnostics/status information Diagnostics indication LED     Ves     ERROR LED Yes     Connection display LINK TX/RX Yes  Supported technology objects Motion Control resources     or the PLC program; selection guide via the TIA Selection     roor SIZER     very objects     Ves, Note: The number of technology objects affects the cycle     time of the PLC program; selection guide via the TIA Selection     roor or SIZER     very objects     very object     very objects     very object     very objects     very object     very objects     very object     v	Diagnostic buffer	
	• present	Yes
Traces         4: Up to 512 KB of data per trace are possible           Interrupts/diagnostics/status information         Ves           PRUNISTOP LED         Yes           • RUNISTOP LED         Yes           • Connection display LINK TX/RX         Yes           Supported technology objects         Yes, Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool or SIZER           • Number of available Motion Control resources for technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool or SIZER           • Number of available Motion Control resources for technology objects         40           - per speed-controlled axis         40           - per synchronous axis         160           - per output cam         20           - per dam track         160           - per dam track         120           - per dam track         120           - per dam track         120           - for each set of kinematics         30           - For each set of kinematics         30           - Per leading axis proxy         3           - Number of positi	<ul> <li>Number of entries, max.</li> </ul>	3 200
• Number of configurable Traces       4; Up to 512 KB of data per trace are possible         Interrupts/diagnostics/indication LED       Ves         • RRNR LED       Yes         • MAINT LED       Yes         • MAINT LED       Yes         • Connection display LINK TX/RX       Yes         Motion Control       Yes: Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool or SIZER         • Number of available Motion Control resources for technology objects affects affects the cycle time of the Selection available Motion Control resources       40         • Per speed-controlled axis       40         • per specific mag axis       80         • per specific mag axis       80         • per specific mag axis       80         • per specific mag axis       160         • per specific mag axis       80         • per specific mag axis       160         • per specific mag axis       160         • per carm track       120         • per carm track       120         • for each set of kinematics       30         • Pro teach carm       7	— of which powerfail-proof	500
Interrupts/diagnostics/status information           Diagnostics indication LED           • RUN/STOP LED         Yes           • ERROR LED         Yes           • MAINT LED         Yes           • Connection display LINK TX/RX         Yes           Supported technology objects         Yes           Motion Control         Yes, Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool or SIZER           • Number of available Motion Control resources for technology objects         2400           • Per speed-controlled axis         40           • per synchronous axis         160           • per synchronous axis         160           • per output cam         20           • per output cam         210           • per output cam         120           • Required Extended Motion Control resources         -           • for each set of kinematics         30           • of reach set of kinematics         30           • Per leading axis proxy         3           • Positioning axis         -           • for each set of kinematics         30           • for each set of kinematics         30           • Pre leading axis proxy         3           • Positioning axis	Traces	
Diagnostics indication LED         Yes           • RUNYSTOP LED         Yes           • ERROR LED         Yes           • MAINT LED         Yes           • Connection display LINK TX/RX         Yes           Supported technology objects         Yes           Motion Control         Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool or SIZER           • Number of available Motion Control resources for technology objects         40           - per speed-controlled axis         40           - per positioning axis         80           - per optical encoder         80           - per output cam         20           - per cam track         160           - per probe         40           • Number of available Extended Motion Control resources         120           - per cam track         160           - per probe         40           • Number of available Extended Motion Control resources         -           - for each cam         2           - for each set of kinematics         30           - Per leading axis proxy         3           • Positioning axis         -           - Number of positioning axes at motion control cycle of 4 ms (typical value) <t< td=""><td><ul> <li>Number of configurable Traces</li> </ul></td><td>4; Up to 512 KB of data per trace are possible</td></t<>	<ul> <li>Number of configurable Traces</li> </ul>	4; Up to 512 KB of data per trace are possible
Diagnostics indication LED         Yes           • RUNYSTOP LED         Yes           • ERROR LED         Yes           • MAINT LED         Yes           • Connection display LINK TX/RX         Yes           Supported technology objects         Yes           Motion Control         Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool or SIZER           • Number of available Motion Control resources for technology objects         40           - per speed-controlled axis         40           - per positioning axis         80           - per optical encoder         80           - per output cam         20           - per cam track         160           - per probe         40           • Number of available Extended Motion Control resources         120           - per cam track         160           - per probe         40           • Number of available Extended Motion Control resources         -           - for each cam         2           - for each set of kinematics         30           - Per leading axis proxy         3           • Positioning axis         -           - Number of positioning axes at motion control cycle of 4 ms (typical value) <t< td=""><td>Interrupts/diagnostics/status information</td><td></td></t<>	Interrupts/diagnostics/status information	
ENCODE LEDYes• ERROR LEDYes• MAINT LEDYes• Connection display LINK TX/RXYesMotion ControlYes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool or SIZER• Number of available Motion Control resources for technology objects2400• Number of available Motion Control resources for technology objects2400• Required Motion Control resources for technology abjects40• per speed-controlled axis40• per synchronous axis160- per output cam20- per cam track160- per cam track160- per cam track120- for each set of kinematics30- for each set of kinematics30- Per leading axis proxy3• Positioning axes at motion control cycle of 4 ms (typical value)7- Number of positioning axes at motion control cycle of 8 ms (typical value)14• PID_CompactYes; Vinversal PID controller with integrated optimization• PID_StepYes; PID controller with integrated optimization for valves		
MAINT LEDYes• Connection display LINK TX/RXYesSupported technology objectsYes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool or SIZERMotion ControlYes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool or SIZER• Number of available Motion Control resources for technology objectsYes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool or SIZER• Number of available Motion Control resources in per speed-controlled axis40• per speed-controlled axis40• per synchronous axis160- per synchronous axis160- per cam track160- per cam track120- per probe40• Number of available Extended Motion Control resources for technology objects- for each cam2- for each cam2- for each set of kinematics30- Per kading axis proxy3• Positioning axis7- Number of positioning axes at motion control cycle of 4 ms (typical value)14- Number of positioning axes at motion control cycle of 4 ms (typical value)Yes; Universal PID controller with integrated optimization• PID_CompactYes; PID controller with integrated optimization for valves• PID_TempYes; PID controller with integrated optimization for valves	• RUN/STOP LED	Yes
Number of available Extended Motion Control         Yes           9         Supported technology objects           9         Motion Control           9         Number of available Motion Control resources         2 400           9         Per synchronous axis         40           9         per synchronous axis         80           9         per synchronous axis         160           9         per external encoder         80           9         per output cam         20           9         per output cam         160           9         per output cam         20           9         per output cam         20           9         per cam track         160           9         per dam track         160           9         per output cam         20           9         per dam track         120           9         per dam track         30           9         per leading axis proxy         3           9         Positioning axis         14           9         per leading axis proxy         14           9         positioning axes at motion control cycle of 4 ms (typical value)         14           9         Posi	• ERROR LED	Yes
Supported technology objects           Motion Control         Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool or SIZER           • Number of available Motion Control resources for technology objects         2 400           • per speed-controlled axis         40           - per speed-controlled axis         80           - per synchronous axis         160           - per output cam         20           - per output cam         20           - per output cam         160           - per output cam         120           - per output cam         120           - per output cam         120           - per output cam         2           - for each set of kinematics         30           - Per leading axis proxy         3           - Number of positioning axes at motion control cycle of 4 ms (typical value)         14           - Number of positioning axes at motion control cycle of 8 ms (typical value)         14           - PID_Compact         Yes; Universal PID controller with integrated optimization           PID_Temp         Yes; PID controller with integrated optimization for te	• MAINT LED	Yes
Motion Control         Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool or SIZER           • Number of available Motion Control resources for technology objects         2 400           • Required Motion Control resources         2 400           — per speed-controlled axis         40           — per synchronous axis         160           — per output cam         20           — per output cam         20           — per output cam         20           — per output cam         180           Per per objects         120           • Number of available Extended Motion Control resources         120           — per cam track         180           — per dading axis proxy         3           • Required Extended Motion Control resources         -           — for each cam         2           — for each cam         3           — Per leading axis proxy         3           • Positioning axis         7           — Number of positioning axes at motion control cycle of 4 ms (typical value)         14           Controller         Yes; Universal PID controller with integrated optimization           • PID_Compact         Yes; PID controller with integrated optimization for valves	<ul> <li>Connection display LINK TX/RX</li> </ul>	Yes
Motion Control         Yes; Note: The number of technology objects affects the cycle time of the PLC program; selection guide via the TIA Selection Tool or SIZER           • Number of available Motion Control resources for technology objects         2 400           • Required Motion Control resources         2 400           — per speed-controlled axis         40           — per synchronous axis         160           — per output cam         20           — per output cam         20           — per output cam         20           — per output cam         180           Per per objects         120           • Number of available Extended Motion Control resources         120           — per cam track         180           — per dading axis proxy         3           • Required Extended Motion Control resources         -           — for each cam         2           — for each cam         3           — Per leading axis proxy         3           • Positioning axis         7           — Number of positioning axes at motion control cycle of 4 ms (typical value)         14           Controller         Yes; Universal PID controller with integrated optimization           • PID_Compact         Yes; PID controller with integrated optimization for valves	Supported technology objects	
Tool or SIZER• Number of available Motion Control resources2 400for technology objects40- per speed-controlled axis40- per speed-controlled axis80- per synchronous axis160- per external encoder80- per output cam20- per cam track160- per grobe40- per probe180- per probe120- for each cam2- for each cam2- for each set of kinematics30- Per leading axis proxy3- Positioning axes at motion control cycle of 8 ms (typical value)14- Number of positioning axes at motion control cycle of 8 ms (typical value)7- ControllerYes; PID controller with integrated optimization for valves+ PID_SatepYes; PID controller with integrated optimization for valves		Yes; Note: The number of technology objects affects the cycle
• Number of available Motion Control resources for technology objects2 400• Required Motion Control resources•- per speed-controlled axis40- per positioning axis80- per synchronous axis160- per external encoder80- per output cam20- per output cam160- per robe40• per probe120• per probe120• Required Extended Motion Control resources for technology objects120- for each cam2- for each cam30- Per leading axis proxy3• Positioning axis7- Number of positioning axes at motion control cycle of 4 ms (typical value) - Number of positioning axes at motion control cycle of 4 ms (typical value)14• PID_CompactYes; PID controller with integrated optimization for valves• PID_TempYes; PID controller with integrated optimization for temperature		
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per speed-controlled axis40per positioning axis80per synchronous axis160per external encoder80per output cam20per cam track180per probe40Number of available Extended Motion Control120resources for technology objects120for each cam2for each cam2for each set of kinematics30Per leading axis proxy3Number of positioning axes at motion control cycle of 4 ms (typical value)7Number of positioning axes at motion control cycle of 8 ms (typical value)14Number of positioning axes at motion control cycle of 8 ms (typical value)7Number of positioning axes at motion control cycle of 8 ms (typical value)14PID_CompactYes; Universal PID controller with integrated optimization for sciPID-TempPID-TempYes; PID controller with integrated optimization for temperature		
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per per synchronous axis160- per synchronous axis160- per external encoder80- per output cam20- per output cam160- per cam track160- per probe40• Number of available Extended Motion Control resources for technology objects120- for each cam2- for each cam2- for each cam30- Per leading axis proxy3• Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value)7- Number of positioning axes at motion control cycle of 8 ms (typical value)14• PID_CompactYes; Universal PID controller with integrated optimization for valves• PID_TempYes; PID controller with integrated optimization for temperature		
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per cam track160- per cam track40- per probe40• Number of available Extended Motion Control resources for technology objects120• Required Extended Motion Control resources for each cam2- for each set of kinematics30- Per leading axis proxy3• Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value)7- Number of positioning axes at motion control cycle of 8 ms (typical value)14• PID_CompactYes; Universal PID controller with integrated optimization• PID_StepYes; PID controller with integrated optimization for valves	— per external encoder	80
	— per output cam	20
ProcessProcess• Number of available Extended Motion Control120resources for technology objects120• Required Extended Motion Control resources for each cam2- for each set of kinematics30- Per leading axis proxy3• Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value)7- Number of positioning axes at motion control cycle of 8 ms (typical value)14• PID_CompactYes; Universal PID controller with integrated optimization for valves• PID_3StepYes; PID controller with integrated optimization for valves• PID-TempYes; PID controller with integrated optimization for temperature	— per cam track	160
resources for technology objectsImage: sequence for each comImage: sequence for each com	— per probe	40
- for each cam2- for each set of kinematics30- Per leading axis proxy3• Positioning axis7- Number of positioning axes at motion control cycle of 4 ms (typical value)7- Number of positioning axes at motion control cycle of 8 ms (typical value)14• PID_CompactVes; Universal PID controller with integrated optimization• PID_3StepYes; PID controller with integrated optimization for valves• PID_TempYes; PID controller with integrated optimization for temperature		120
- for each set of kinematics30- Per leading axis proxy3• Positioning axis Number of positioning axes at motion control cycle of 4 ms (typical value)7- Number of positioning axes at motion control cycle of 8 ms (typical value)14Controller-• PID_CompactYes; Universal PID controller with integrated optimization Yes; PID controller with integrated optimization for valves• PID_TempYes; PID controller with integrated optimization for temperature	<ul> <li>Required Extended Motion Control resources</li> </ul>	
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<ul> <li>Positioning axis         <ul> <li>Number of positioning axes at motion control cycle of 4 ms (typical value)</li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> </ul> </li> <li>Number of positioning axes at motion control cycle of 8 ms (typical value)</li> <li>Controller</li> <li>PID_Compact</li> <li>PID_3Step</li> <li>PID-Temp</li> <li>Yes; PID controller with integrated optimization for valves</li> <li>Yes; PID controller with integrated optimization for valves</li> </ul>	— for each set of kinematics	30
- Number of positioning axes at motion control cycle of 4 ms (typical value)7- Number of positioning axes at motion control cycle of 8 ms (typical value)14Controller14• PID_CompactYes; Universal PID controller with integrated optimization• PID_3StepYes; PID controller with integrated optimization for valves• PID-TempYes; PID controller with integrated optimization for valves	— Per leading axis proxy	3
- Number of positioning axes at motion control cycle of 4 ms (typical value)7- Number of positioning axes at motion control cycle of 8 ms (typical value)14Controller14• PID_CompactYes; Universal PID controller with integrated optimization• PID_3StepYes; PID controller with integrated optimization for valves• PID-TempYes; PID controller with integrated optimization for valves	<ul> <li>Positioning axis</li> </ul>	
- Number of positioning axes at motion control cycle of 8 ms (typical value)14Controller·• PID_CompactYes; Universal PID controller with integrated optimization• PID_3StepYes; PID controller with integrated optimization for valves• PID-TempYes; PID controller with integrated optimization for temperature		7
Controller       • PID_Compact       Yes; Universal PID controller with integrated optimization         • PID_3Step       Yes; PID controller with integrated optimization for valves         • PID-Temp       Yes; PID controller with integrated optimization for temperature	— Number of positioning axes at motion	14
• PID_3Step       Yes; PID controller with integrated optimization for valves         • PID-Temp       Yes; PID controller with integrated optimization for temperature	Controller	
PID-Temp     Yes; PID controller with integrated optimization for temperature	PID_Compact	Yes; Universal PID controller with integrated optimization
PID-Temp     Yes; PID controller with integrated optimization for temperature	PID_3Step	Yes; PID controller with integrated optimization for valves
		Yes; PID controller with integrated optimization for temperature
	•	

• High-speed co	unter
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Yes

• High-speed counter		
Standards, approvals, certificates		
Highest safety class achievable in safety mode		
<ul> <li>Performance level according to ISO 13849-1</li> </ul>	PLe	
• SIL acc. to IEC 61508	SIL 3	
Probability of failure (for service life of 20 years and	repair time of 100 hours)	
<ul> <li>Low demand mode: PFDavg in accordance with SIL3</li> </ul>	< 2.00E-05	
<ul> <li>High demand/continuous mode: PFH in accordance with SIL3</li> </ul>	< 1.00E-09	
Ambient conditions		
Ambient temperature during operation		
<ul> <li>horizontal installation, min.</li> </ul>	0 °C	
<ul> <li>horizontal installation, max.</li> </ul>	60 °C; Display: 50 °C, at an operating temperature of typically 50 °C, the display is switched off	
<ul> <li>vertical installation, min.</li> </ul>	0°0	
<ul> <li>vertical installation, max.</li> </ul>	40 °C; Display: 40 °C, at an operating temperature of typically 40 °C, the display is switched off	
Ambient temperature during storage/transportation		
● min.	-40 °C	
• max.	70 °C	
Altitude during operation relating to sea level		
<ul> <li>Installation altitude above sea level, max.</li> </ul>	5 000 m; Restrictions for installation altitudes > 2 000 m, see manual	
Configuration		
Programming		
Programming language		
— LAD	Yes; incl. failsafe	
— FBD	Yes; incl. failsafe	
— STL	Yes	
— SCL	Yes	
— GRAPH	Yes	
Know-how protection		
<ul> <li>User program protection/password protection</li> </ul>	Yes	
Copy protection	Yes	
Block protection	Yes	
Access protection		
Password for display	Yes	
Protection level: Write protection	Yes	
<ul> <li>Protection level: Read/write protection</li> </ul>	Yes	
Protection level: Write protection for Failsafe	Yes	

<ul> <li>Protection level: Complete protection</li> </ul>	Yes
Cycle time monitoring	
lower limit	adjustable minimum cycle time
• upper limit	adjustable maximum cycle time
Dimensions	
Width	70 mm
Height	147 mm
Depth	129 mm
Weights	
Weight, approx.	830 g
last modified:	08/25/2020